Ω Metrohm

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1   Purpose

This document describes new functions, changes, and improvements in the following firmware version:

- 57.1008.0023 for OS version 008

In comparison with the firmware version:

- 57.1008.0022 for OS version 008

2   New functions

The following new functions have been integrated:

- New message integrated: **Initialization failed, adjustment of servo motor incomplete. Contact your regional Metrohm service representative.**

3   Improvements

The following improvements have been made:

- The message **The system is shutting down** has been changed to **Instant Up is activated**.

  The display and controls can be deactivated by pressing the ⏻ button without switching off the device completely. This functionality already exists, now under the new **Instant Up** designation.
- The message **The system is switching off** has been changed to **The device is switching off**.
- The term *buret* has been removed or replaced by a more appropriate term.
- Translations implemented in 13 languages (except Czech).

4   Fixed bugs

The following bugs have been fixed:

- The pause set in the start conditions is executed correctly (TITR-30998).
- The problem with movements of the flat stopcock and system crash during ADD has been fixed (TITR-30920).

- For **Subnet mask** in the Ethernet settings, the IP address entered is displayed, no longer just the default IP address.

5   Known issues

The following bugs are known:

- The recalculation slightly modifies the x-axis of the curve (for 10 mL stop volume).